

FIR

$$y_k = \underbrace{\delta_0 \mu(u_k)} + \underbrace{\delta_1 \mu(u_{k-1})} + \dots + \delta_{s-1} \mu(u_{k-(s-1)}) + z_k =$$

$$= \gamma_0 \left[ q_1 \varphi_1(u_k) + q_2 \varphi_2(u_k) + \dots + q_m \varphi_m(u_k) \right]$$

$$+ \delta_1 \left[ q_1 \varphi_1(u_{k-1}) + q_2 \varphi_2(u_{k-1}) + \dots + q_m \varphi_m(u_{k-1}) \right]$$

+ ...

$$+ \delta_{s-1} \left[ q_1 \varphi_1(u_{k-(s-1)}) + \dots + q_m \varphi_m(u_{k-(s-1)}) \right] + z_k =$$

$$\mu(u) = q_1 \varphi_1(u) + \dots + q_m \varphi_m(u)$$

$$= \underbrace{\begin{bmatrix} \delta_0 q_1 \\ \delta_0 q_2 \\ \vdots \\ \delta_0 q_m \\ \delta_1 q_1 \\ \vdots \\ \delta_1 q_m \\ \vdots \\ \delta_{s-1} q_1 \\ \delta_{s-1} q_2 \\ \vdots \\ \delta_{s-1} q_m \end{bmatrix}}_{\Theta}^T \underbrace{\begin{bmatrix} \varphi_1(u_k) \\ \vdots \\ \varphi_m(u_k) \\ \varphi_1(u_{k-1}) \\ \vdots \\ \varphi_m(u_{k-1}) \\ \vdots \\ \varphi_1(u_{k-(s-1)}) \\ \vdots \\ \varphi_m(u_{k-(s-1)}) \end{bmatrix}}_{\Phi} + z_k = \Theta^T \Phi + z_k$$

$\varphi$

$\phi$

$$\mathbf{Y}_N = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_N \end{bmatrix}$$

$\Phi_N$

$$\Phi_N = \begin{bmatrix} \phi_1^T \\ \phi_2^T \\ \vdots \\ \phi_N^T \end{bmatrix}$$

$N$

$S \cdot m$

$$\hat{\Theta} = (\Phi_N^T \Phi_N)^{-1} \Phi_N^T \mathbf{Y}_N$$